

BUFFER MANAGEMENT FOR DATA TRANSFERS BETWEEN A HOST DEVICE AND A STORAGE MEDIUM

FIELD OF THE INVENTION

5 The present invention relates to data transfers between a host device and a storage medium.

BACKGROUND OF THE INVENTION

10 Memory controllers are used for transferring data between a host device and a non-volatile semiconductor memory device. Such memory controllers typically contain a buffer for temporarily storing data that is in the process of being written to or read from the memory device. Errors sometimes occur during data transfers between the host and the memory device. Some errors may occur when data that is in the buffer is overwritten prior to being transferred out of the buffer. Other errors
15 occur when an attempt is made to transfer the wrong data or non-existent data out of the buffer. Therefore, there exists a need for systems and methods for buffer management that solve these and other problems associated with memory controllers.

SUMMARY OF THE INVENTION

20 The present invention relates to systems and methods for transferring data between a host device and a storage medium. In this regard, an embodiment of one such method includes receiving from a host device a command to transfer data between the host device and a storage medium, and storing in a register a value for determining a buffer's fullness.

25 An embodiment of a system for transferring data between a host device and a storage medium includes a host interface that receives from the host device a command to transfer data between the host device and the storage medium, a buffer that temporarily stores data that is transferred between the host device and the storage medium, and a register that stores a value for determining the buffer's fullness.

BRIEF DESCRIPTION OF THE DRAWINGS

30 The present invention, as defined in the claims, can be better understood with reference to the following drawings. The drawings are not necessarily to scale,

emphasis instead being placed on clearly illustrating the principles of the present invention.

FIG. 1 is a block diagram of a computer network 100 in accordance with one embodiment of the present invention.

FIG. 2 is a block diagram depicting an embodiment of the data transfer system depicted in FIG. 1.

FIG. 3 is a flow chart depicting a method that may be implemented by the data transfer system depicted in FIG. 2.

FIG. 4 is a block diagram depicting an embodiment of the host interface of the data transfer system depicted in FIG. 2.

FIG. 5 is a block diagram depicting an embodiment of the data mover of the data transfer system depicted in FIG. 2.

FIG. 6 is a block diagram depicting an embodiment of the storage medium interface of the data transfer system depicted in FIG. 2.

FIGS. 7A, 7B, and 7C are flow charts depicting a non-limiting example of a method for writing data to the storage medium depicted in FIG. 1 in accordance with an embodiment of the present invention.

FIGS. 8A, 8B, and 8C are flow charts depicting a non-limiting example of a method for reading data from the storage medium depicted in FIG. 1 in accordance with an embodiment of the present invention.

DETAILED DESCRIPTION

FIG. 1 is a block diagram of a computer network 100 in accordance with one embodiment of the present invention. The computer network 100 comprises a host 102 and a storage medium (SM) 104 that are coupled to a data transfer system (DTS) 200. In an alternative embodiment, the Storage Medium 104 and/or the Data Transfer System 200 may be part of the host 102. The Data Transfer System 200 facilitates read and write data transfers between the host 102 and the Storage Medium 104. For example, in a write operation, data is transferred from the host 102 to the Storage Medium 104 via the Data Transfer System 200. Similarly, in a read operation, data is transferred from the Storage Medium 104 to the host 102 via the Data Transfer System 200. The host 102 is a data processing system such as, for example, a desktop computer, a notebook computer, a personal digital assistant (PDA), or a mainframe computer, among others. The Storage Medium 104 is preferably a non-

volatile semiconductor memory device such as, for example, flash memory, non-volatile random access memory (non-volatile RAM), or electrically erasable programmable read only memory (EEPROM), among others.

FIG. 2 is a block diagram depicting one embodiment of the Data Transfer System 200 (FIG. 1). The Data Transfer System 200 includes a data mover (DM) module 500, a host interface (HI) module 400, a storage medium interface (SMI) module 600, a buffer 205 (preferably a circular buffer), a microprocessor 201, memory 202, and a bus 204. As indicated in FIG. 2, the components of the Data Transfer System 200 may be coupled as follows: the Data Mover 500 is coupled to the Host Interface 400 and to the Storage Medium Interface 600; the Host Interface 400 is coupled to a host 102 (FIG. 1); the Storage Medium Interface 600 is coupled to a Storage Medium 104 (FIG. 1); the microprocessor 201 is coupled to the memory 202; and the Host Interface 400, the Data Mover 500, and the Storage Medium Interface 600 are coupled to the microprocessor 201 via the bus 204. The Data Mover 500 organizes and controls the flow of data between the host 102 and the Storage Medium 104. The buffer 205 is used to buffer data being transferred between the host 102 and the Storage Medium 104. The memory 202 is used for storing a data transfer program 203 that is executed by a microprocessor 201 to control the operation of the Host Interface 400, the Data Mover 500, and the Storage Medium Interface 600. In a preferred embodiment, the memory 202 comprises random access memory (RAM) and read only memory (ROM), and the data transfer program 203 comprises firmware. The buffer 205, the Host Interface 400, the Data Mover 500, the Storage Medium Interface 600, the microprocessor 201, the memory 202, and the bus 204 are preferably, but not necessarily, part of a single application specific integrated circuit (ASIC).

FIG. 3 depicts a flow chart that illustrates a method 300 that may be implemented by the Data Transfer System 200 (FIG. 2) in accordance with one embodiment of the invention. In step 301, the Data Transfer System 200 receives a read or write command from the host 102 (FIG. 1) requesting a read or write operation, respectively. In response to receiving the command, the microprocessor 201 (FIG. 2) loads registers in the Host Interface 400, the Data Mover 500, and the Storage Medium Interface 600 (FIG. 2) for executing the read or write operation requested by the command. In a read operation, data is transferred from the Storage Medium 104 (FIG. 1) to the host 102. During a write operation, data is transferred

from the host 102 to the Storage Medium 104. After the registers are loaded in step 302, a data unit (e.g., a block or a sector of data) is transferred between the Data Transfer System 200 and the host 102 or the Storage Medium 104, as indicated in step 303. The data transfer is coordinated and managed by the Host Interface 400, the Data Mover 500, and/or the Storage Medium Interface 600. Data that is transferred between the host 102 and the Storage Medium 104 is buffered in the buffer 205 of the Data Transfer System 200. In one implementation of the method 300, a data unit that is transferred between the buffer 205 and the host 102 is a block of data that may comprise multiple sectors, whereas a data unit that is transferred between the buffer 205 and the storage medium 104 is a sector (e.g. 512 bytes). Data is preferably transferred between the Data Transfer System 200 and the host 102 in units of bytes (8 bits) or words (16 bits), and between the Data Transfer System 200 and the storage medium 104 in units of bytes. After each unit of data is transferred between the Data Transfer System 200 and the host 102 or the Storage Medium 104, registers in the Host Interface 400, the Data Mover 500, and/or the Storage Medium Interface 600 are updated in step 304 to reflect the occurrence of the data transfer. After the registers are updated, a determination is made by the data mover 500 in step 305 as to whether the entire read or write operation requested by the read or write command, respectively, is complete. If the entire read or write operation is complete, then the microprocessor 201 is interrupted in step 306, and the method 300 terminates in step 307. If, however, the read or write operation is not complete, then the method 300 repeats steps 303-305 until the read or write operation is complete.

FIG. 4 is a block diagram illustrating selected components of the Host Interface 400 of the Data Transfer System 200 (FIG. 2) in accordance with one embodiment of the present invention. The Host Interface 400 interfaces with the host 102 (FIG. 1) and facilitates data transfers between the host 102 and the buffer 205 (FIG. 2). The Host Interface 400 and the Data Mover 500 (FIG. 5) transmit signals to each other in order to indicate their respective status and their readiness to perform a certain step. For instance, an H_XferBlk signal 403 from the Data Mover 500 to the Host Interface 400 indicates that the buffer 205 is ready to provide or receive data to/from the host 102. On the other hand, an H_BlkXferred signal 404 from the Host Interface 400 to the Data Mover 500 indicates that a block of data has been transferred between the buffer 205 and the host 102.

The Host Interface 400 includes a WordsPerBlk register 401 that is loaded at the beginning of a read or write operation with the number of words per block of data. A WordCtr register 402 is used for counting down the number of words transferred during each block transfer. Prior to each block transfer, the WordCtr register 402 is loaded by receiving a value contained in the WordsPerBlk register 401. In an alternative embodiment, the WordsPerBlk register 401 is loaded with the number of longwords per block of data, and the WordCtr register 402 is used for counting down the number of longwords transferred during each block transfer.

FIG. 5 is a block diagram depicting selected components of the Data Mover 500 in accordance with one embodiment of the present invention. The Data Mover 500 includes registers containing information as described in the following table:

Table 1, Registers that may be included in the Data Mover 500

REGISTER NAME	CONTENT/DESCRIPTION
Host_LW_Ptr 511	Data buffer 205 long word address for transfers to/from host 102
Host_LW_Ctr 513	Long word counter for transfers to/from host 102
Host_LW_PerBlk 506	The number of long words per block of data
HostXferSectCtr (HXSC) 502	Counts number of sectors to be transferred to/from host 102
SectsPerBlk (SPB) 504	Number of sectors per block of data
SOB_LW_Ptr 515	Start address of buffer 205
EOB_LW_Ptr 516	End address of buffer 205
SMI_LW_Ptr 512	Data buffer 205 long word address for transfers to/from Storage Medium 104
SMI_LW_Ctr 514	Long word counter for transfers to/from Storage Medium 104
SMI_LW_PerSect 507	The number of long words per sector.
BuffSects 505	Number of sectors in the buffer 205
MaxBuffSects 510	Size of the buffer 205
DeviceXferSectCtr (DXSC) 503	Counts number of sectors to be transferred to/from Storage Medium 104

The registers identified in Table 1 are used by the Data Mover 500 to manage the transfer of data between the host 102 and the Storage Medium 104. A data transfer between the host 102 and the Storage Medium 104 is initiated in response to the Host Interface 400 receiving a read or write command from the host 102. After the Host Interface 400 receives a read or write command from the host 102, the Host Interface 400 interrupts the microprocessor 201 which loads certain registers of the modules Host Interface 400, Data Mover 500, and Storage Medium Interface 600 and then activates them (the modules 400, 500, and 600). After being activated, the Data Mover 500 sends a request for a block of data to the Host Interface 400 (for a write operation) or a request for a sector of data to the Storage Medium Interface 600 (for a read operation). A request for a block from the Host Interface 400 is achieved by sending an H_XferBlk 403 signal to the Host Interface 400, whereas a request for a sector from the Storage Medium Interface 600 is achieved by sending an SMI_XferSect 508 signal to the Storage Medium Interface 600.

For a read operation, if there is room in the data transfer buffer 205 and if the value of DXSC 503 is greater than 0, then the Data Mover 500 requests that a sector of data be transmitted from the Storage Medium 104 to the buffer 205. The Data Mover 500 performs this request by sending an SMI_XferSect 508 signal to the Storage Medium Interface 600. The Data Mover 500 also tracks the progress of the sector transfer by managing the DXSC 503, which the Data Mover 500 decrements by 1 after each successful sector transfer from the Storage Medium 104 to the buffer 205. Eventually the DXSC 503 will go to 0, and the Data Mover 500 will stop transmitting data transfer requests to the Storage Medium Interface 600. Similarly, for a write operation, as long as there is room in the data transfer buffer 205 and the value of HXSC is greater than the value of SPB 504, the Data Mover 500 hardware will continue to request that a block of data be transmitted from the host 102 to the buffer 205 by sending an H_XferBlk signal to the Host Interface 400. The Data Mover 500 will also track the progress of the transfer by managing the HXSC 502, which is decremented by the value of SPB after each successful block transfer from the host 102 to the buffer 205. Eventually the HXSC 502 will go to 0, and the Data Mover 500 will stop transmitting data transfer requests to the Host Interface 400.

Data transfers between the data transfer buffer 205 and the Host Interface 400 or Storage Medium Interface 600 are preferably in units of longwords (e.g., 4 bytes).

As each longword is transferred, Data Mover 500 hardware decrements either the Host_LW_Ctr 513 or the SMI_LW_Ctr 514 depending on whether the transfer is to/from the host 102 or the Storage Medium 104. In addition, word counters internal to the Host Interface 400 and Storage Medium Interface 600 are decremented. At the end of a sector transfer to/from the Storage Medium 104, the Storage Medium Interface 600's internal word counter goes to 0, prompting it to send the sector acknowledgment SMI_SectXferred 509 to the Data Mover 500, which is expecting this signal because its own SMI_LW_Ctr 514 has gone to 0. If there are more sectors to be transferred (i.e., if the value of DXSC 503 is greater than 0), then upon receipt of the SMI_SectXferred 509 signal, the Data Mover 500 hardware reloads the SMI_LW_Ctr 514 from the register SMI_LW_PerSect 507 and issues another SMI_XferSect 508 signal to the Storage Medium Interface 600. Similarly, at the end of a block transfer to/from the host 102, the internal word counter WordCtr 402 of the Host Interface 400 goes to 0, prompting the Host Interface 400 to send the block acknowledgment Host_BlkJXferred 404 to the Data Mover 500 which is expecting this signal because its Host_LW_Ctr 513 has also gone to 0. If there are more blocks to be transferred, then upon receipt of the Host_BlkJXferred 404 signal, the Data Mover 500 hardware reloads the Host_LW_Ctr 513 from the register Host_LW_PerBlk 506 and issues another Host_XferBlk 403 signal to the Host Interface 400.

FIG. 6 is a block diagram illustrating selected components of the Storage Medium Interface 600 of the Data Transfer System 200 (FIG. 2) in accordance with one embodiment of the present invention. The Storage Medium Interface 600 interfaces with Storage Medium 104 (FIG. 1) and transfers data between the buffer 205 (FIG. 2) and the Storage Medium 104 in response to receiving an SMI_XferSect signal 508 from the Data Mover 500. After the Storage Medium Interface 600 transfers a sector of data between the buffer 205 and the Storage Medium 104, it transmits an SMI_SectXferred signal 509 to the Data Mover 500 confirming the data transfer. Registers contained in the Storage Medium Interface 600 include an SMI_XferLen register 601 that indicates the number of data sectors to be transferred and an SMI_XferCtr register 602 that counts down the number of sectors transferred. The SMI_XferCtr register 602 is loaded with the value contained in the SMI_XferLen register 601 prior to each read or write operation.

With additional reference to FIG. 5 throughout the remaining figure descriptions, FIGS. 7A, 7B, and 7C are flow charts depicting a non-limiting example of a write method that is performed by the Data Transfer System 200 (FIG. 2) in accordance with one embodiment of the present invention. In step 701, the Host Interface 400 (FIG. 2) receives a write command from a host 102 (FIG. 1). In response to receiving the write command, the Host Interface 400 interrupts the Microprocessor 201 (FIG. 2) which, in step 702, loads the number of sectors per block into SectsPerBlk (SPB 504), the transfer length in sectors into HostXferSectCtr (HXSC 502) and DeviceXferSectCtr (DXSC 503), the number of longwords in a sector into SMI_LW_PerSect 507, and the number of longwords in a block into Host_LW_PerBlk 506. In addition, the Microprocessor 201 sets BuffSects 505 to MaxBuffSects 510, sets Host_LW_Ptr 511 and SMI_LW_Ptr 512 to SOB_LW_Ptr 515, and then activates the modules Host Interface 400, Data Mover 500, and Storage Medium Interface 600 (FIG. 2).

Subsequently, in step 703, the Data Mover 500 determines if the amount of data remaining to be transferred is less than a block's worth of data; this determination is based on whether the value of HXSC 502 is less than the value of SPB 504. If the value of HXSC 502 is less than the value of SPB 504, then the method 700 proceeds to step 715 (FIG. 7C). If, however, the value of HXSC 502 is not less than the value of SPB 504, then the Data Mover 500 determines in step 704 if there is at least 1 block's worth of available storage in the buffer 205; this determination is based on whether the value of BuffSects 505 is greater than or equal to the value of SPB 504. If the value of BuffSects 505 is not greater than or equal to the value of SPB 504, then the method 700 proceeds to step 708 (FIG. 7B).

If the value of BuffSects 505 is greater than or equal to the value of SPB 504, then the Data Mover 500 sends an H_XferBlk 403 signal to the Host Interface 400 requesting that the Host Interface 400 transfer a block of data from the host 102 to the buffer 205, as indicated in step 705. After the H_XferBlk 403 signal is sent to the Host Interface 400, a block of data is transferred from the host 102 to the buffer 205 in step 706 and the Data Mover 500 receives an H_BlkJXferred 404 signal from the Host Interface 400 confirming the data transfer. After the H_BlkJXferred 404 signal is received by the Data Mover 500 from the Host Interface 400, the values of HXSC 502 and BuffSects 505 are decreased by the value of SPB 504, as indicated in step

707. In addition, if the value of Host_LW_Ptr 511 is equal to EOB_LW_Ptr 516, then the value of Host_LW_Ptr 511 is set equal to SOB_LW_Ptr 515.

The Data Mover 500 then determines in step 708 (FIG. 7B) if data sectors remain to be transferred to the Storage Medium 104 (FIG. 1); this determination is based on whether the value of DXSC 503 is greater than 0. If the value of DXSC 503 is not greater than 0, then the Storage Medium Interface 600 interrupts the microprocessor 201 in step 709 and the method 700 terminates in step 710. If, however, the value of DXSC 503 is greater than 0, then the Data Mover 500 determines in step 711 if there is at least one sector of data in the buffer 205; this determination is based on whether the value of BuffSects 505 is less than the value of MaxBuffSects 510.

If the value of BuffSects 505 is less than the value of MaxBuffSects 510, then the Data Mover 500 sends an SMI_XferSect 508 signal to the Storage Medium Interface 600 requesting that the Storage Medium Interface 600 transfer a sector of data from the buffer 205 to the Storage Medium 104, as indicated in step 712. However, if the value of BuffSects 505 is not less than the value of MaxBuffSects 510, then the method 700 returns to step 703 (FIG. 7A). After the Storage Medium Interface 600 receives an SMI_XferSect 508 signal, the Storage Medium Interface 600 transfers a sector of data from the buffer 205 to the Storage Medium 104, as indicated in step 713, and then sends an SMI_SectXferred 509 signal to the Data Mover 500 confirming the transfer. After the SMI_SectXferred 509 signal is received by the Data Mover 500, the value of DXSC 503 is decreased by 1 and the value of BuffSects 505 is increased by 1, as indicated in step 714. In addition, if the value of SMI_LW_Ptr 512 is equal to EOB_LW_Ptr 516, then the value of SMI_LW_Ptr 512 is set equal to SOB_LW_Ptr 515.

At step 715 (FIG. 7C), the Data Mover 500 determines if there is a runt block remaining to be transferred. A runt block is an amount of data that is less than the unit of data (e.g. block) that the host 102 uses in sending or receiving data to the Data Transfer System 200. The determination of whether a runt block remains to be transferred is based on whether the value of HXSC 502 is greater than 0. If the value of HXSC 502 is not greater than 0, then the method 700 proceeds to step 708 (FIG. 7B). If, however, the value of HXSC 502 is greater than 0, then the Data Mover 500 interrupts the microprocessor 201 in step 716. After being interrupted, the microprocessor 201 reloads SPB 504 with HXSC 502 and Host_LW_PerBlk 506 with

a value equal to the value of HXSC 502 multiplied by the value of SMI_LW_PerSect 507 (i.e. Host_LW_PerBlk 506 is loaded with a value equal to the number of longwords remaining to be transferred). After SPB 504 and Host_LW_PerBlk 506 are reloaded, the method 700 returns to step 703 so that the runt block may be transferred. After the runt block is transferred, the microprocessor 201 reloads SPB 504 and Host_LW_PerBlk 506 with the values that they had prior to when the microprocessor 201 was interrupted in step 716. In one possible implementation, the microprocessor is not interrupted in step 716; instead, SPB 504 and Host_LW_PerBlk 506 are reloaded prior to the runt block transfer using a specialized circuit without microprocessor 201 intervention.

FIGS. 8A, 8B, and 8C are flow charts depicting a non-limiting example of a read method that is performed by the Data Transfer System 200 (FIG. 2) in accordance with one embodiment of the present invention. In step 801, the Host Interface 400 (FIG. 2) receives a read command from a host 102 (FIG. 1). In response to receiving the read command, the Host Interface 400 interrupts the microprocessor 201 (FIG. 2) which, in step 802, loads the number of sectors per block into SPB 504, the transfer length in sectors into HXSC 502 and DXSC 503, the number of longwords in a sector into SMI_LW_PerSect 507, and the number of longwords in a block into Host_LW_PerBlk 506. In addition, the Microprocessor 201 sets BuffSects 505 to 0, sets Host_LW_Ptr 511 and SMI_LW_Ptr 512 to SOB_LW_Ptr 515, and then activates the modules Host Interface 400, Data Mover 500, and Storage Medium Interface 600 (FIG. 2).

The Data Mover 500 then determines in step 803 if data sectors are to be received from the Storage Medium 104 (FIG. 1); this determination is based on whether the value of DXSC 503 is greater than 0. If the value of DXSC 503 is not greater than 0, then the method 800 proceeds to step 808 (FIG. 8B). If the value of DXSC 503 is greater than 0, then the Data Mover 500 determines in step 804 if there is space in the buffer 205 for receiving a sector of data from the Storage Medium 104; this determination is based on whether the value of BuffSects 505 is less than the value of MaxBuffSects 510.

If the value of BuffSects 505 is not less than the value of MaxBuffSects 510, then the method 800 proceeds to step 808. However, if the value of BuffSects 505 is less than the value of MaxBuffSects 510, then the Data Mover 500 sends an SMI_XferSect 508 signal to the Storage Medium Interface 600 requesting that the

Storage Medium Interface 600 transfer a sector of data from the Storage Medium 104 to the buffer 205, as indicated in step 805. After the Storage Medium Interface 600 receives the SMI_XferSect 508 signal, the Storage Medium Interface 600 transfers a sector of data from the Storage Medium 104 to the buffer 205, as indicated in step 806, and then sends an SMI_SectXferred 509 signal to the Data Mover 500 confirming the transfer. After the SMI_SectXferred 509 signal is received by the Data Mover 500 from the Storage Medium Interface 600, the value of DXSC 503 is decreased by 1 and the value of BuffSects 505 is increased by 1, as indicated in step 807. In addition, if the value of SMI_LW_Ptr 512 is equal to EOB_LW_Ptr 516, then the value of SMI_LW_Ptr 512 is set equal to SOB_LW_Ptr 516.

Subsequently, in step 808 (FIG. 8B), the Data Mover 500 determines if the amount of data remaining to be transferred is less than a block's worth of data. This determination is based on whether the value of HXSC 502 is less than the value of SPB 504. If the value of HXSC 502 is less than the value of SPB 504, then the method 800 proceeds to step 815 (FIG. 8C). If, however, the value of HXSC 502 is not less than the value of SPB 504, then the Data Mover 500 determines in step 809 if there is at least 1 block's worth of data in the buffer 205; this determination is based on whether the value of BuffSects 505 is greater than or equal to the value of SPB 504. If the value of BuffSects 505 is not greater than or equal to the value of SPB 504, then the method 800 proceeds to step 803 (FIG. 8A). However, if the value of BuffSects 505 is greater than or equal to the value of SPB 504, then the Data Mover 500 sends an H_XferBlk 403 signal to the Host Interface 400 requesting that the Host Interface 400 transfer a block of data from the buffer 205 to the host 102, as indicated in step 810. After the H_XferBlk 403 signal is sent to the Host Interface 400, a block of data is transferred from the buffer 205 to the host 102 in step 811 and the Data Mover 500 receives an H_BlkJXferred 404 signal from the Host Interface 400 confirming the data transfer. After the H_BlkJXferred 404 signal is received by the Data Mover 500 from the Host Interface 400, the values of HXSC 502 and BuffSects 505 are decreased by the value of SPB 504, as indicated in step 812. In addition, if the value of Host_LW_Ptr 511 is equal to EOB_LW_Ptr 516, then the value of Host_LW_Ptr 511 is set to SOB_LW_Ptr 515. After the register values are adjusted in step 812, the method 800 returns to step 803 (FIG. 8A).

At step 815 (FIG. 8C), the Data Mover 500 determines if there is a runt block remaining to be transferred. The determination of whether a runt block remains to be

transferred is based on whether the value of HXSC 502 is greater than 0. If the Data Mover 500 determines in step 815 that the value of HXSC 502 is not greater than 0, then the Data Mover 500 interrupts the microprocessor 201 in step 818 and the method 800 terminates in step 819. If, however, the value of HXSC 502 is greater than 0, then the Data Mover 500 interrupts the microprocessor 201 in step 816. After being interrupted, the microprocessor 201 reloads SPB 504 with HXSC 502 and reloads Host_LW_PerBlk 506 with a value equal to the value of HXSC 502 multiplied by the value of SMI_LW_PerSect 507 (i.e., Host_LW_PerBlk 506 is loaded with a value equal to the number of longwords remaining to be transferred). After SPB 504 and Host_LW_PerBlk 506 are reloaded, the method 800 returns to step 808 so that the runt block may be transferred. After the runt block is transferred, the microprocessor 201 reloads SPB 504 and Host_LW_PerBlk 506 with the values that they had prior to when the microprocessor 201 was interrupted in step 816. In one possible implementation, the microprocessor is not interrupted in step 816. Instead, SPB 504 and Host_LW_PerBlk 506 are reloaded prior to the runt block transfer using a specialized circuit without microprocessor 201 intervention.

In an alternative embodiment of the Data Transfer System 200, functions or steps shown in the flow charts depicted in FIGS. 7A, 7B, 7C, 8A, 8B, and 8C may be executed out of order from that shown or discussed, including substantially concurrently or in reverse order as would be understood by those reasonably skilled in the art.

It should be emphasized that the above-described embodiments of the present invention are merely possible examples, among others, of the implementations, setting forth a clear understanding of the principles of the invention. Many variations and modifications may be made to the above-described embodiments of the invention without departing substantially from the principles of the invention. All such modifications and variations are intended to be included herein within the scope of the disclosure and present invention and protected by the following claims.